

Evaluation and monitoring of free running oscillators serving as source of randomness

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Jittery clock – commonly used source of randomness in digital devices

- Clock jitter caused by several noise sources
 - ▶ White noise (thermal noise, ...)
 - ↪ Best source of randomness, non manipulable
 - ▶ Autocorrelated noise (low frequency noises, e.g. flicker noise)
 - ↪ Entropy rate (unpredictability measure) difficult to quantify
 - ▶ Data dependent noise
 - ↪ Dangerous (manipulable), must be avoided

Jitter monitoring

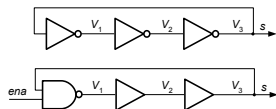
- Continuous embedded monitoring is preferable
- Jitter – usually quantified using the variance

$$\text{var}(X) = \mathbb{E}(X^2) - [\mathbb{E}(X)]^2 \quad (1)$$

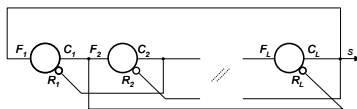
Introduction

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Free running oscillators – sources of the jittery clocks

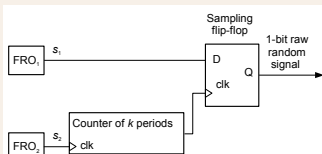


Ring oscillators (RO)

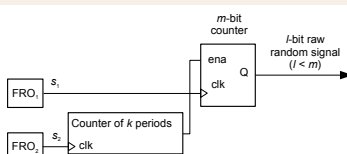


Self-timed ring (STR) based on Müller gates

Randomness extraction methods from jittery clocks



Sampler based randomness extraction



Counter based randomness extraction

Objectives

- Analyze the use of variance for entropy estimation
- Use high order Markov model to estimate entropy coming from auto-correlated noises
- Compare performance of ROs and STRs as sources of randomness

- 1 Variance and Allan variance
- 2 High order Markov model for entropy rate estimation from autocorrelated signals
- 3 Experimental results

Characterization of random fluctuations of the clock frequency

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Power spectral density (PSD)

- Defined as:

$$S_y(f) = h_\alpha f^\alpha \quad (2)$$

- y – dimensionless fractional frequency ($y = (\nu - \nu_0)/\nu_0$)
 - α – constant characterizing the noise process
 - h_α – intensity of this noise
- Characterizes random fluctuations of the clock frequency

α	Type of the noise process
-2	Random Walk Frequency (RWF)
-1	Flicker Noise Frequency (FF)
0	White Noise Frequency (WF) or Random Walk Phase (RWP)
1	Flicker Noise Phase (FP)
2	White Noise Phase (WP)

Variance of the frequency fluctuations

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Main assumption

- y is an infinite zero-mean stationary process
 - ▶ characterized by its variance computed from a window of length τ

Variance can be computed using the power spectral density

- Corollary of the Wiener-Khinchin theorem
- Variance of y computed from the power spectral density $S_y(f)$:

$$\sigma_y^2(\tau) = \int_0^{+\infty} S_y(f) \times |H_\tau(f)|^2 df, \quad (3)$$

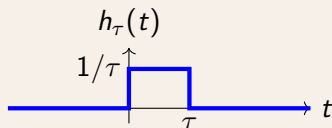
whenever it exists.

- ▶ $H_\tau(f)$ is the transfer function of the variance operator:
 - ↪ Fourier transform of the impulse response function h_τ
 - ↪ Depends on the type of variance computed

Computation of the statistical variance from the PSD

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Time domain



Frequency domain

$$|H_\tau(f)|^2 = \left(\frac{\sin(\pi\tau f)}{\pi\tau f} \right)^2 \quad (4)$$

Variance of the jitter computed for $\alpha \in [-2; 2]$ from time window τ

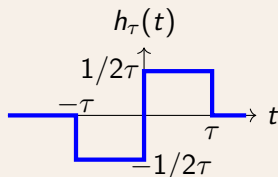
$$\sigma_y^2(\tau) = \sum_{\alpha=-2}^2 \frac{h_\alpha}{(\pi\tau)^2} \int_0^{f_h} f^{\alpha-2} \sin^2(\pi\tau f) df. \quad (5)$$

- Problem: if $\alpha \leq -1$, the integral does not converge as f tends to 0
 - ▶ The use of the statistical variance can cause entropy overestimation

Allan variance and its computation from the PSD

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Time domain



Frequency domain

$$|H_{\tau}(f)|^2 = \left(\frac{\sin(\pi\tau f)}{\pi\tau f} \right)^2 \sin^2(\pi\tau f) \quad (6)$$

Allan Variance of the jitter computed for $\alpha \in [-2; 2]$ from window τ

$$\sigma_y^2(\tau) = \sum_{\alpha=-2}^2 \frac{2h_{\alpha}}{(\pi\tau)^2} \int_0^{f_h} f^{\alpha-2} \sin^4(\pi\tau f) df \quad (7)$$

- Convergence ensured for $\alpha > -3$ as f tends to 0:
 - ▶ Allan variance is accurate, even in presence of low frequency noises

Allan variance estimation from a limited data set

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An average fractional frequency can be used

- Average frequency deviation \bar{y}_k over a time interval of length τ
 - ▶ Corresponds to the fluctuations while counting the number of periods of the jittery signal over τ

- Estimate of the Allan variance:

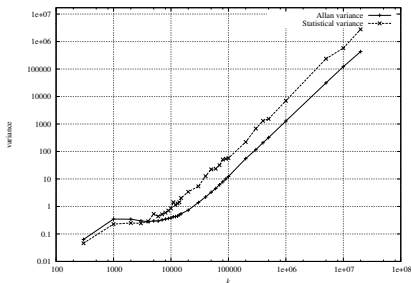
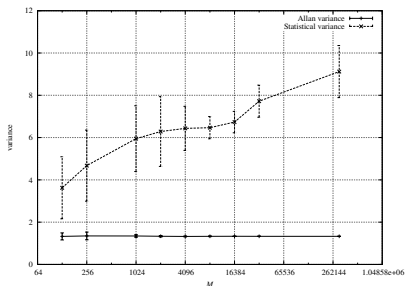
$$\sigma_y^2(\tau) = \frac{1}{2(M-1)} \sum_{i=1}^{M-1} (\bar{y}_{i+1} - \bar{y}_i)^2. \quad (8)$$

↪ M : total number of \bar{y}_k 's.

- For $\alpha = 0$, $\sigma_y^2(\tau)$ is an unbiased estimator of the variance even for a finite M

Experimental results

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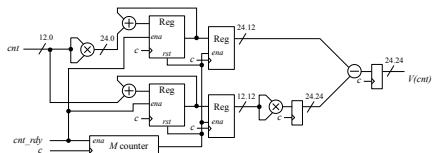


- Variance dependence on the number of samples M
 - ▶ Allan variance stable
 - ▶ Statistical variance increases with M
- Variance dependence on the jitter accumulation period k
 - ▶ Allan variance always below statistical variance
 - ▶ Statistical variance causes entropy rate overestimation
- Similar results for both types of free running oscillators studied

Hardware implementations

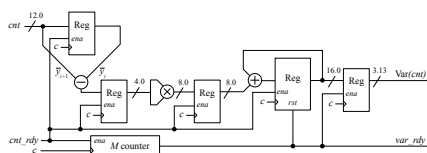
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- Statistical variance



3 adders/subtractors, 2 multipliers

- Allan variance



1 adder/subtractor, 1 multiplier

Comparison with the state-of-the-art methods

Method	Area		f_{max}	Power
	ALM/Regs	DSPs	[MHz]	[mW]
Haddad <i>et al.</i>	119/160	2	178.3	6-7
Fischer and Lubicz	169/200	4	187.7	7-8
Proposed method, Eq. (8)	49/117	1	238.5	4-5

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The use of high order Markov chain models for entropy estimation

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Min-entropy

- Min-entropy is the most conservative entropy measure
 - ▶ Avoids entropy rate overestimation
 - ▶ Hard to estimate in general
- Recent approach offers efficient way to estimate min-entropy^a:
 - ▶ Information sources modeled as high order Markov chains

^aS. Kamath and S. Verdu, Estimation of entropy rate and Renyi entropy rate for Markov chains, IEEE International Symposium on Information Theory 2016

Markov chain

- Convenient to model temporal short-term dependencies
 - ▶ Higher order models give more accuracy but are much more complex
- Depending on jitter properties and the randomness extraction process, we use an 8-th order Markov model to study dependencies
 - ▶ Model parameters: $\{0, 1\}^8$ states, transition matrix $2^8 \times 2^8$

Entropy estimates from the 8-th order Markov chain model

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Randomness extraction method: sampling the jittery clock

Jitter accumulation time	Markov chain	AIS 31 Procedure B	AIS 31 T8	NIST 800-90B	NIST 800-90B
Periods of s_2	min-entropy		Shannon entropy	IID	min-entropy
10 000	0.8102	failed	0.9844	non-IID	0.648
20 000	0.8105	failed	0.9851	non-IID	0.647
30 000	0.8102	failed	0.9847	non-IID	0.648
50 000	0.9369	failed	0.9992	non-IID	0.673
100 000	0.9012	failed	0.9935	non-IID	0.670

Randomness extraction method: counting the jittery clock periods

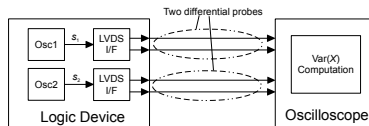
Jitter accumulation time	Markov chain	AIS 31 Procedure B	AIS 31 T8	NIST 800-90B	NIST 800-90B
Periods of s_2	min-entropy		Shannon entropy	IID	min-entropy
10 000	0.8089	failed	0.9966	non-IID	0.844
15 000	0.9769	passed	0.9998	non-IID	0.931
20 000	0.9865	passed	0.9999	IID	0.999
25 000	0.9907	passed	0.9999	IID	0.998
100 000	0.9910	passed	0.9999	IID	0.998

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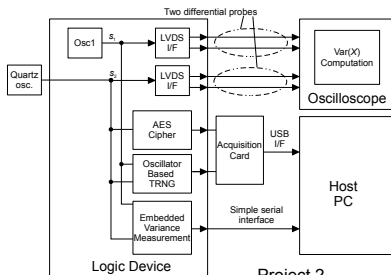
Impact of the surrounding logic on the jitter and entropy rate

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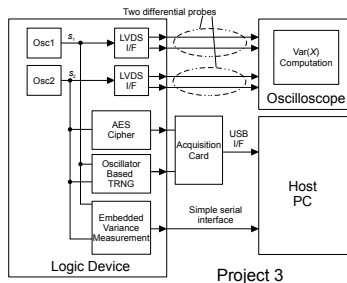
- Three projects implemented
- Blocks placed exactly on the same place in the same FPGA



Project 1



Project 2



Project 3

Impact of the surrounding logic on the jitter and entropy rate

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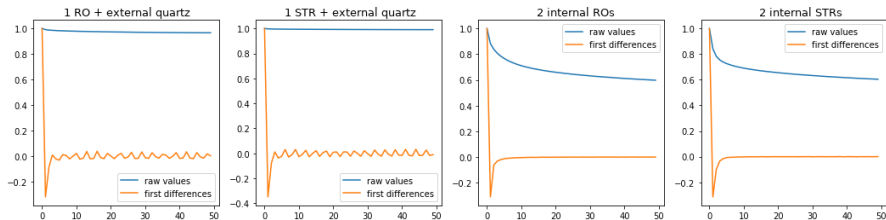
Project	σ_1 [ps]	σ_2 [ps]	$Var(cnt)$	$Avar(N)$
Project 1 (just two rings)	3.9	3.3	14.01	2.79
Project 2 (ring + ext.osc. + other logic)	9.7	7.3	26.94	4.33
Project 3 (two rings + other logic)	10.6	10.0	14.72	2.76

- Oscillator jitter increases when a full cryptosystem is implemented
 - ▶ Surrounding logic has inevitable impact on clock jitters
- However, variances of counter values do not change when both oscillators are implemented inside the device!
- External clocks
 - ▶ Cause entropy rate overestimation
 - ▶ Introduce manipulable global noise sources into the generator

Comparison of RO and STR as sources of randomness

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- Autocorrelation of raw counter values and their first differences
 - ▶ Two identical rings (RO or STR)
 - ▶ One ring (RO or STR) and an external quartz oscillator



- RO and STR exhibit the same behavior in terms of jitter produced
- The use of identical oscillators reduces autocorrelations
- First order difference removes large portion of autocorrelation

Conclusions

- **Counting jittery clock periods** gives higher quality random numbers
 - ▶ Higher bit rate with higher entropy rate
 - ▶ Counter values can be used for online jitter monitoring
- **Allan variance** should be used to estimate entropy rate rather than the statistical variance
 - ▶ Not sensitive to window size – impact of low frequency noises can be reduced using small windows without losing precision
 - ▶ Smaller circuitry required for implementation
- **Differential principle of the TRNG design** is a stringent requirement, not a recommendation
 - ▶ Global, manipulable noises are strong and always present
- **High order Markov chain models** provide good min-entropy estimates and are efficient to detect dependencies in generated numbers

Acknowledgments



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HECTOR

Hardware Enabled Crypto and Randomness

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www.hector-project.eu

